

FIG. 1



One shot

FIG. 2

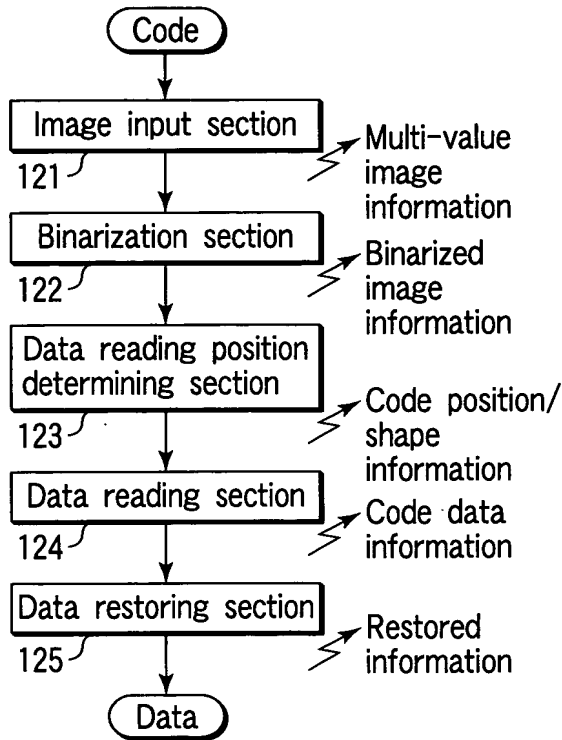


FIG. 3

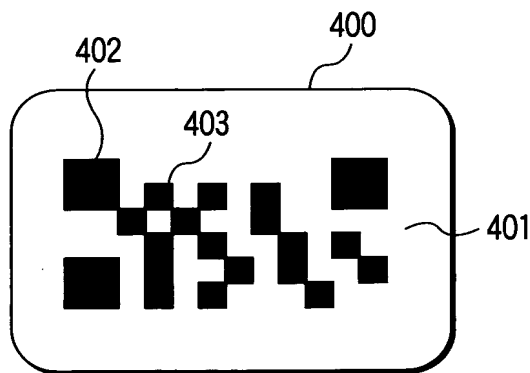
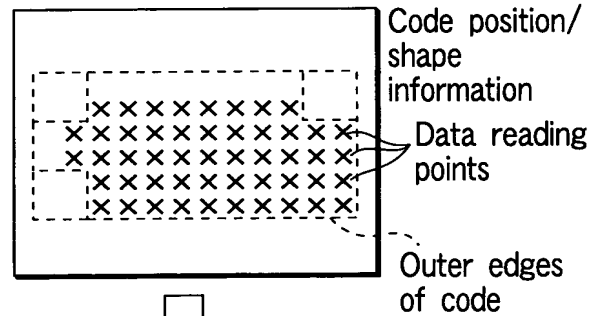
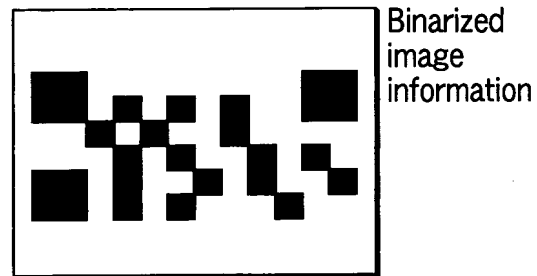
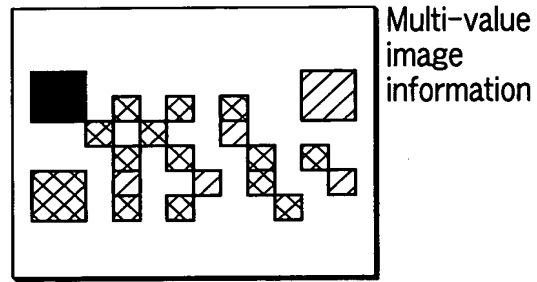


FIG. 4



0 1 0 1 0 1 0 0  
 0 1 0 1 0 0 1 0 0 0 0  
 0 0 1 0 1 0 0 1 0 1 0  
 0 1 0 0 1 0 1 0 0 1  
 0 1 0 1 0 0 0 1 0 0

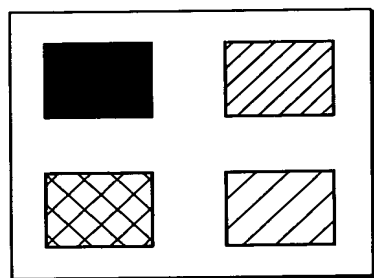
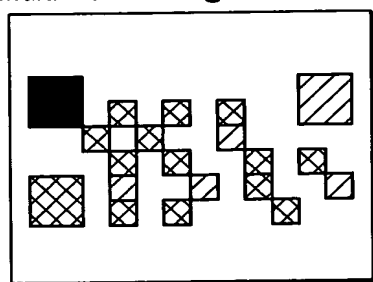
Code data information

"This code is"

Restored information

FIG. 5

Multi-value image information



Average brightness of predetermined region

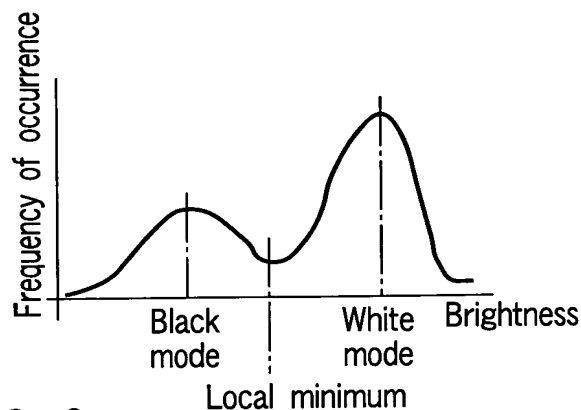
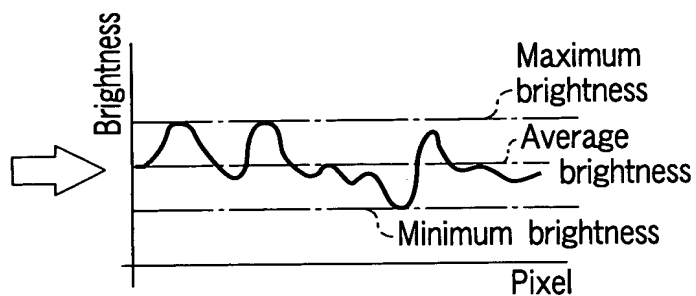
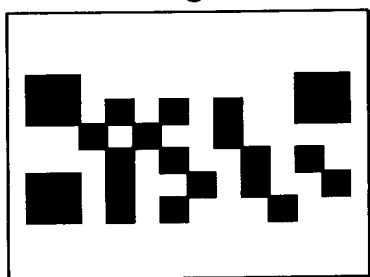


FIG. 6

Binarized image information



Black : 55	Black : 30
White : 45	White : 70
Black : 50	Black : 40
White : 50	White : 60

Pixel distribution in predetermined region

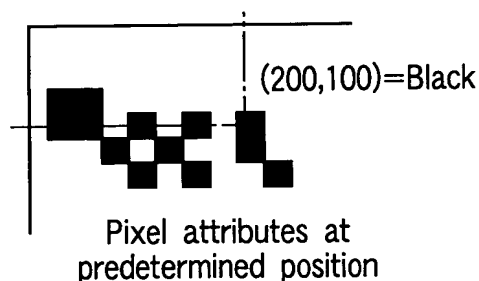
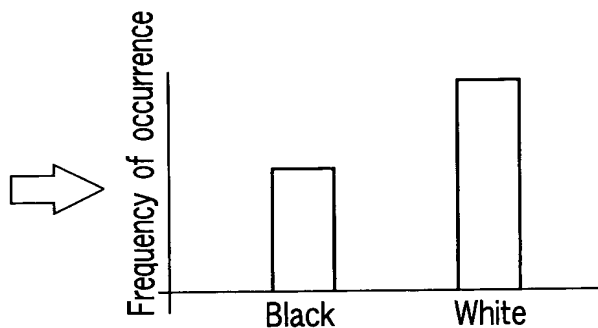
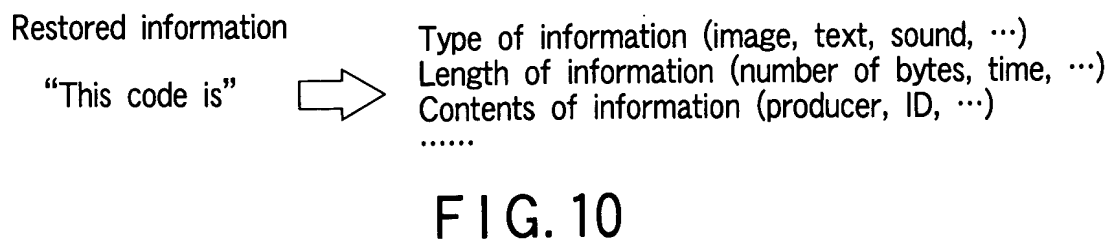
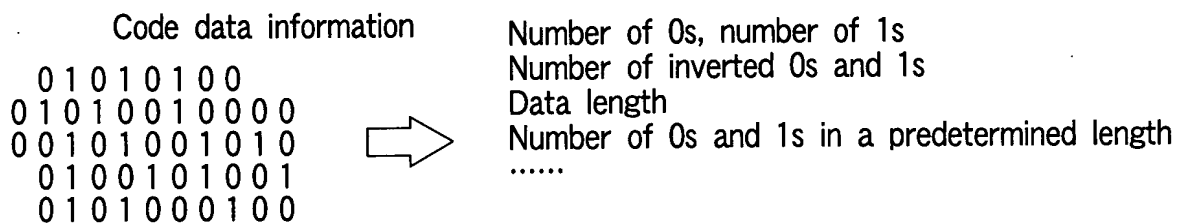
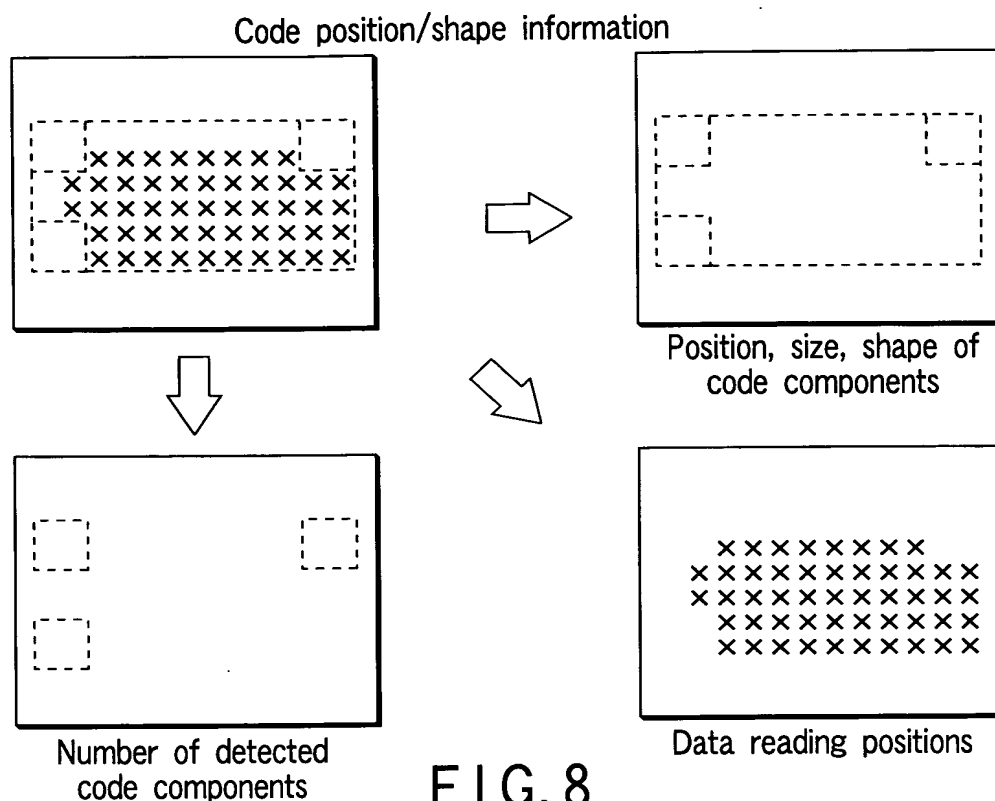


FIG. 7



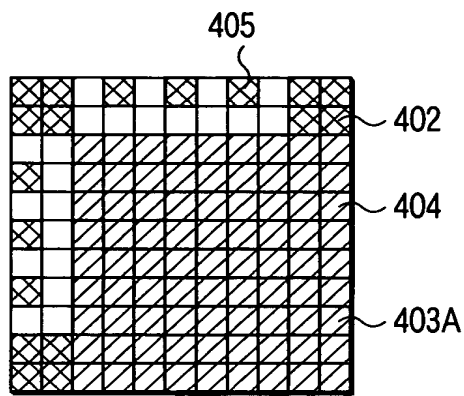


FIG. 11  
PRIOR ART

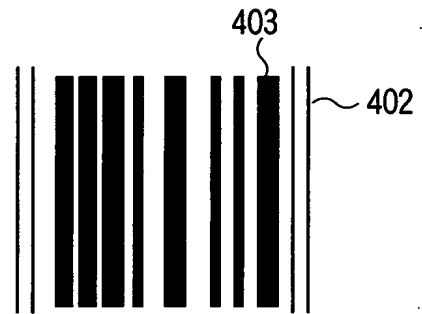


FIG. 12  
PRIOR ART

FIG. 13  
PRIOR ART

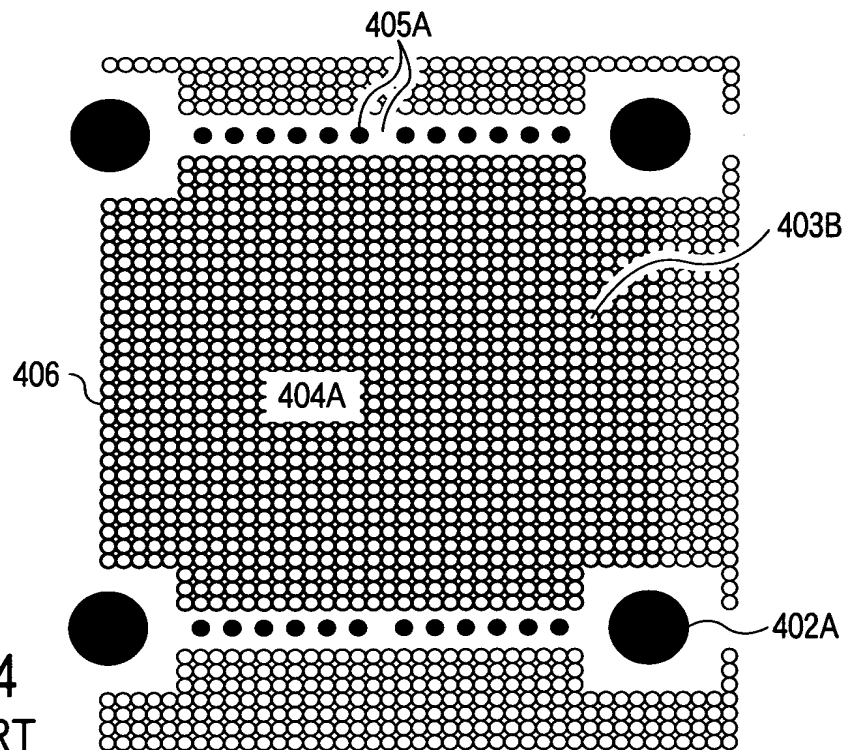
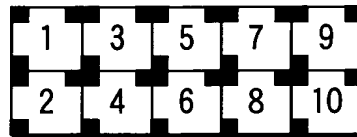


FIG. 14  
PRIOR ART

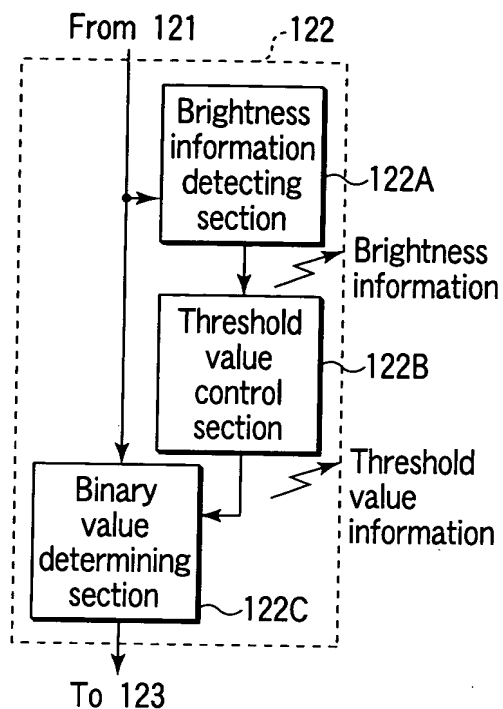


FIG. 15

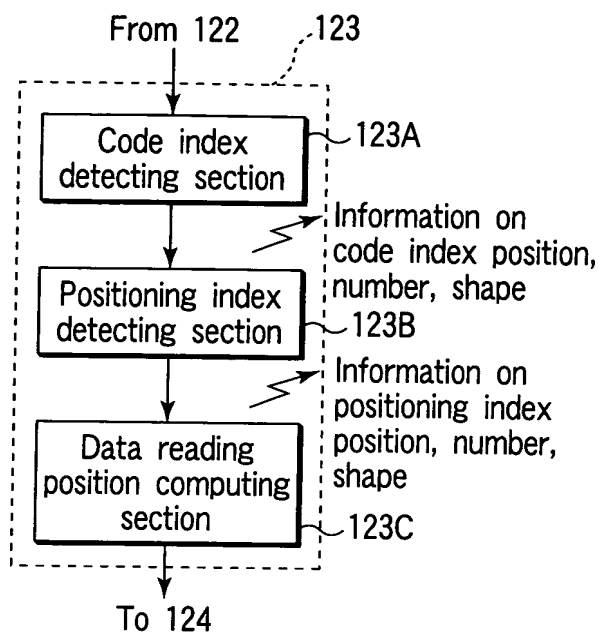


FIG. 16

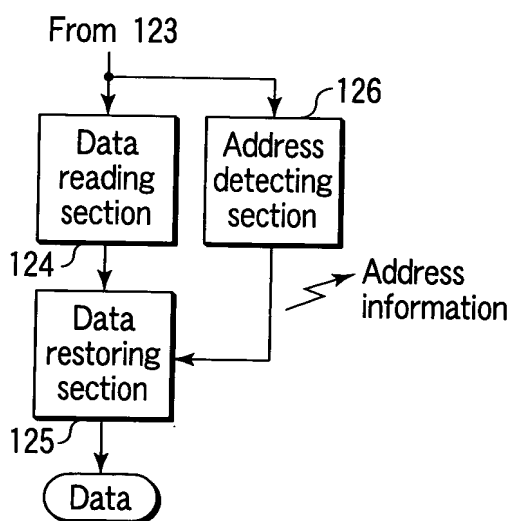


FIG. 17

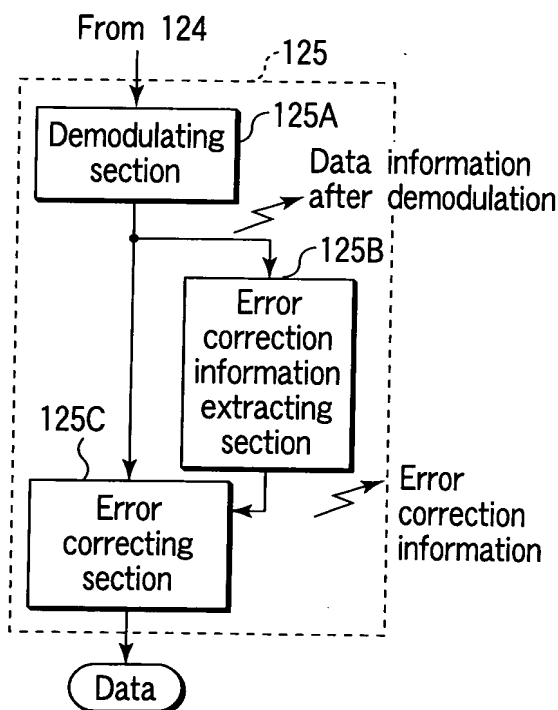


FIG. 18

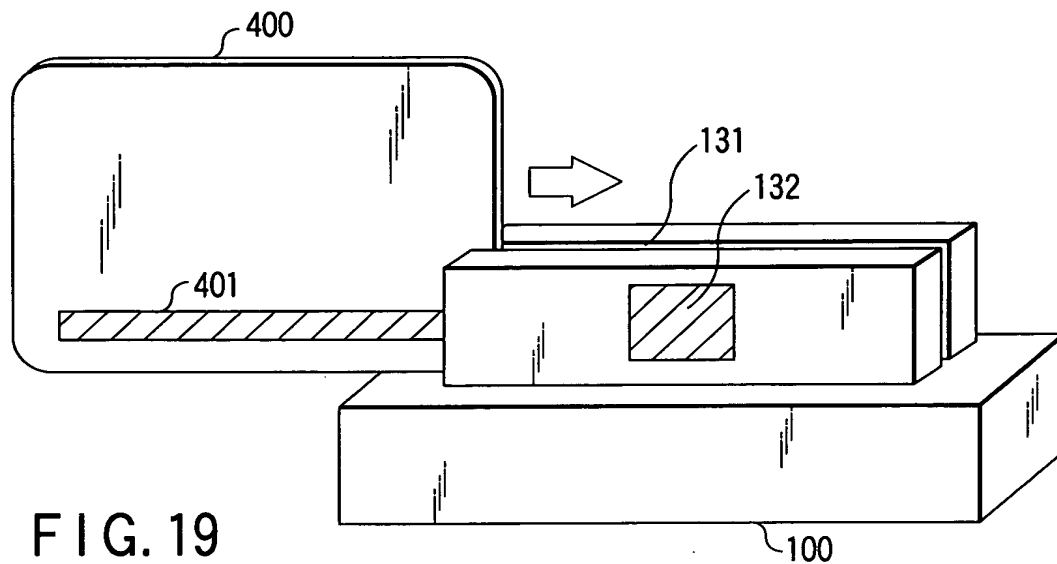


FIG. 19

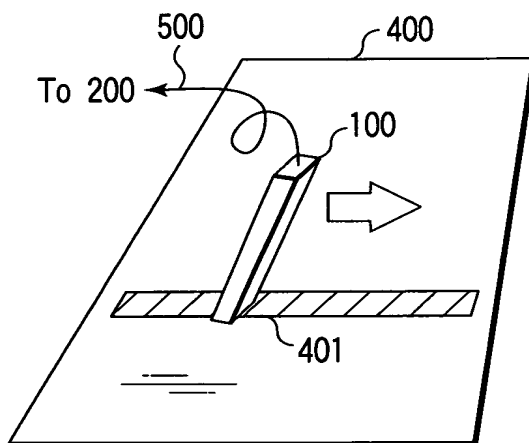


FIG. 20

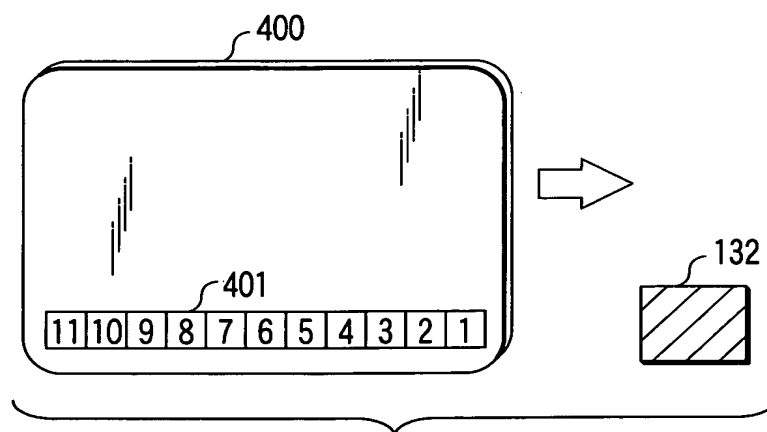
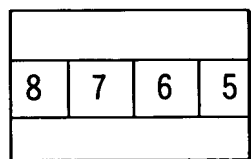
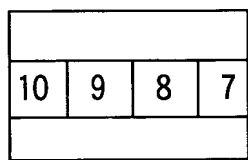


FIG. 21



Picked up image

FIG. 22



Picked up image

FIG. 23

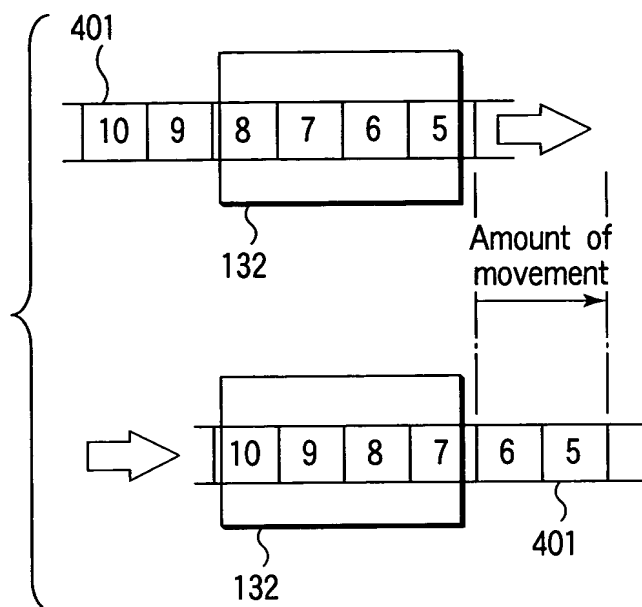


FIG. 24

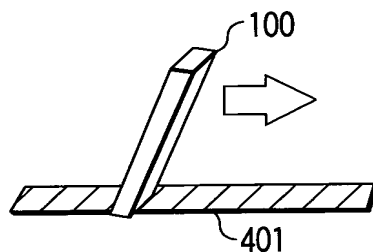


FIG. 25

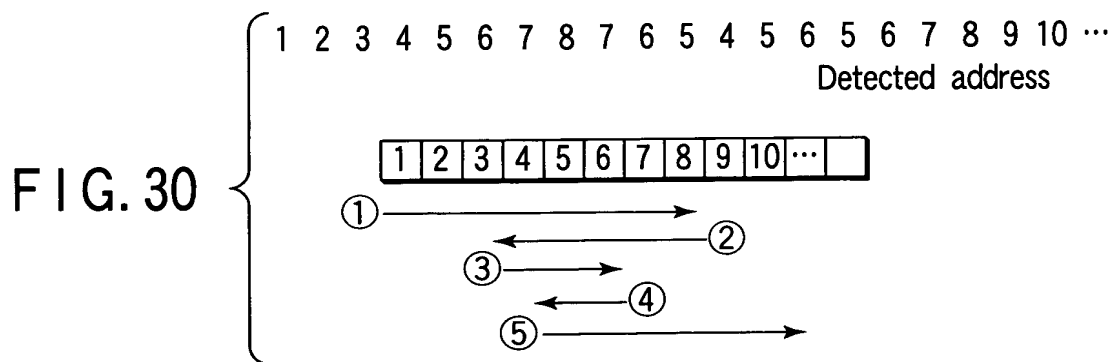
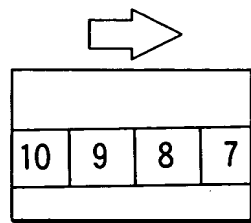


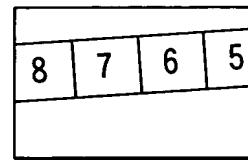
FIG. 30





Picked up image

FIG. 26



Picked up image

FIG. 27

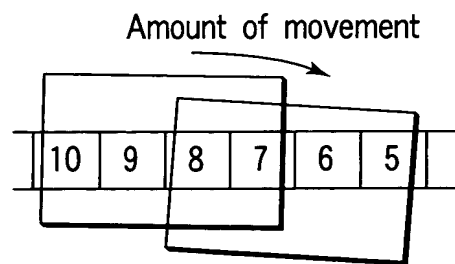
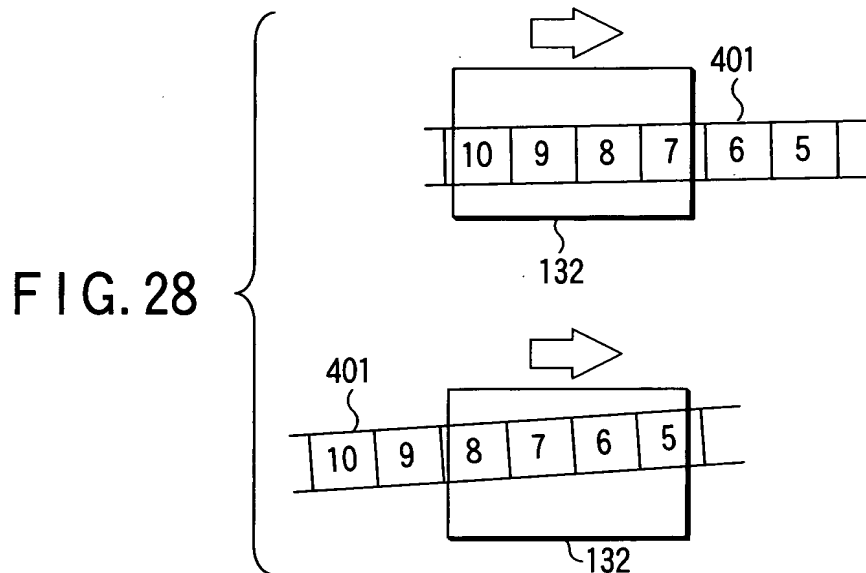


FIG. 29

Picked up images

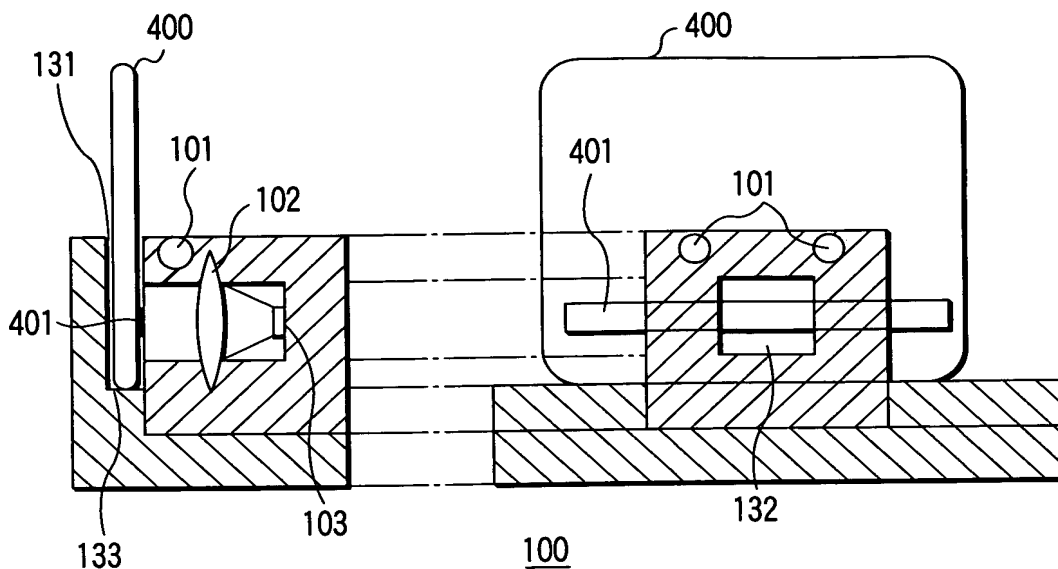
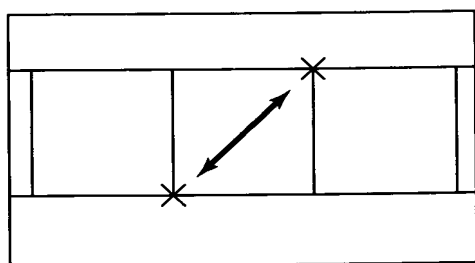
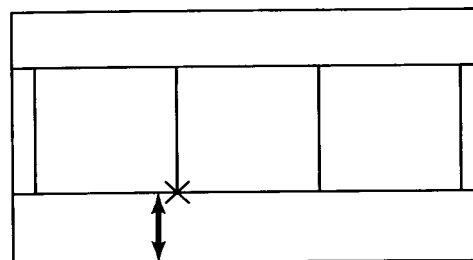


FIG. 31



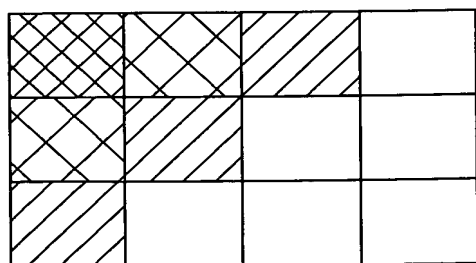
Parameter relating to  
lens magnification

FIG. 32



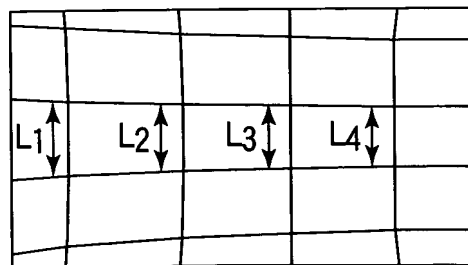
Parameter relating to  
guide position

FIG. 33



Parameter relating to  
lighting condition

FIG. 34



Parameter relating to  
distortion

FIG. 35

Detected information	Acquired parameter	Parameter relating to code reading operation	Parameter relating to way of reading code	Parameter relating to recording medium	Parameter relating to code reading apparatus
Environment information	Reading environment (temperature; humidity; time; position; atmospheric pressure)	○			○
	Power supply rising time; supply voltage				○
Multi-value image information	Maximum brightness (suspension, tilt; lighting intensity, sensor sensitivity; reflectivity)	○	○	○	○
	Minimum brightness (suspension, tilt; lighting intensity, sensor sensitivity; reflectivity)	○	○	○	○
	Average brightness (suspension, tilt; lighting intensity, sensor sensitivity; reflectivity)	○	○	○	○
	Brightness distribution (suspension, tilt; lighting intensity, sensor sensitivity; reflectivity)	○	○	○	○
	Average brightness of predetermined region	○	○	○	○
	Ratio of maximum brightness/minimum brightness (density)			○	
	Brightness of code components	○	○	○	○

FIG. 36A



Code data information	Data reading positions			
	Number of black dots, number of white dots			
	Black/white ratio			
	Data length			
	Number of read blocks			
Demodulated data information	Number of 1s; number of 0s			
	1/0 ratio			
Error correction information	Number of corrected errors (missing data)			
	Positions of corrected errors			
Restored information	ID; producer; type of information			
	Recording time; amount of data			
Relative movement information	Moving speed			
	Moving direction			
	Number of movements			
	Meandering			
	Time spent from command input to shooting of code at predetermined			

○ represents particularly effective parameter

FIG. 36C



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FIG. 39

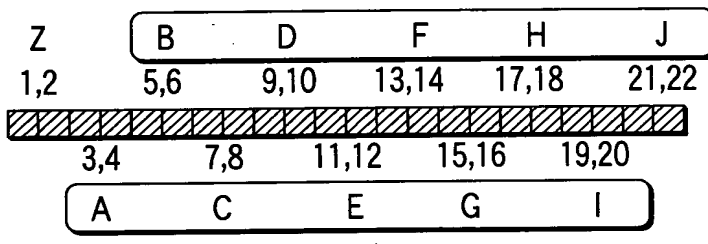
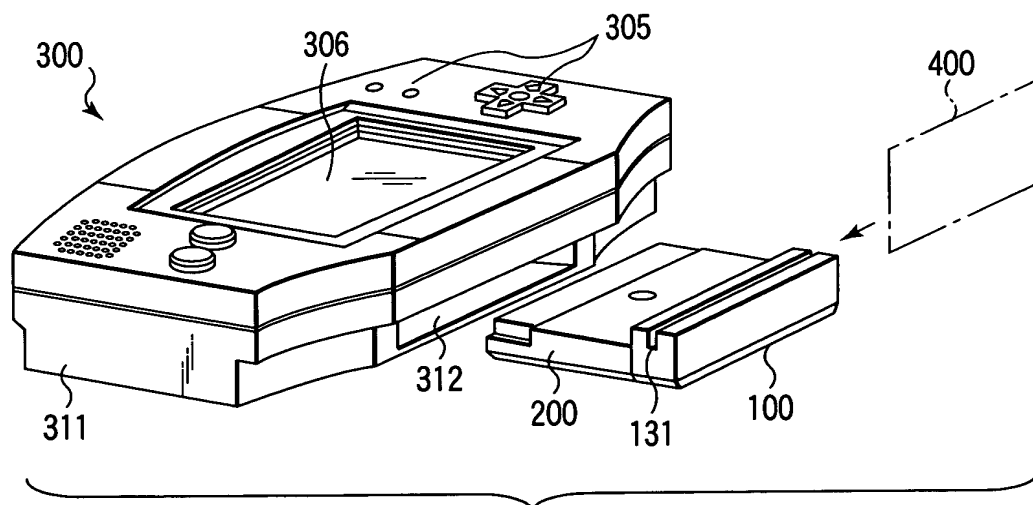


FIG. 40



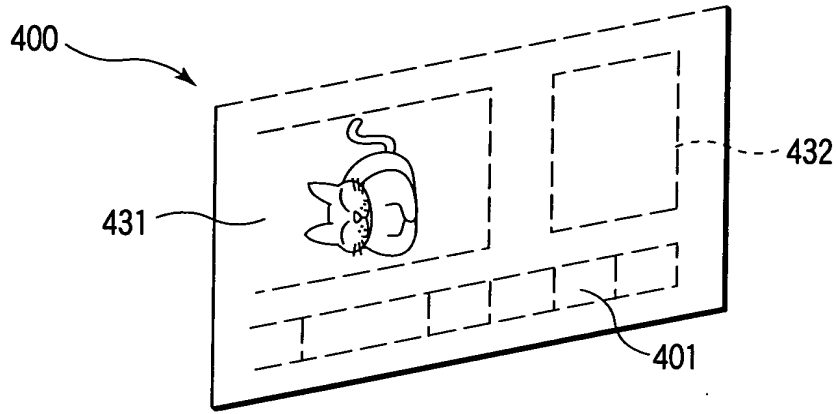


FIG. 41

Card ID	Attribute	Data section
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- Information to be provided with randomness + plurality of pieces of information to be used for providing randomness
- Information to be provided with randomness + program adapted to select a plurality of motions
- Information to be provided with randomness + program adapted to handle a plurality of program parameters

FIG. 42



20100922-030102

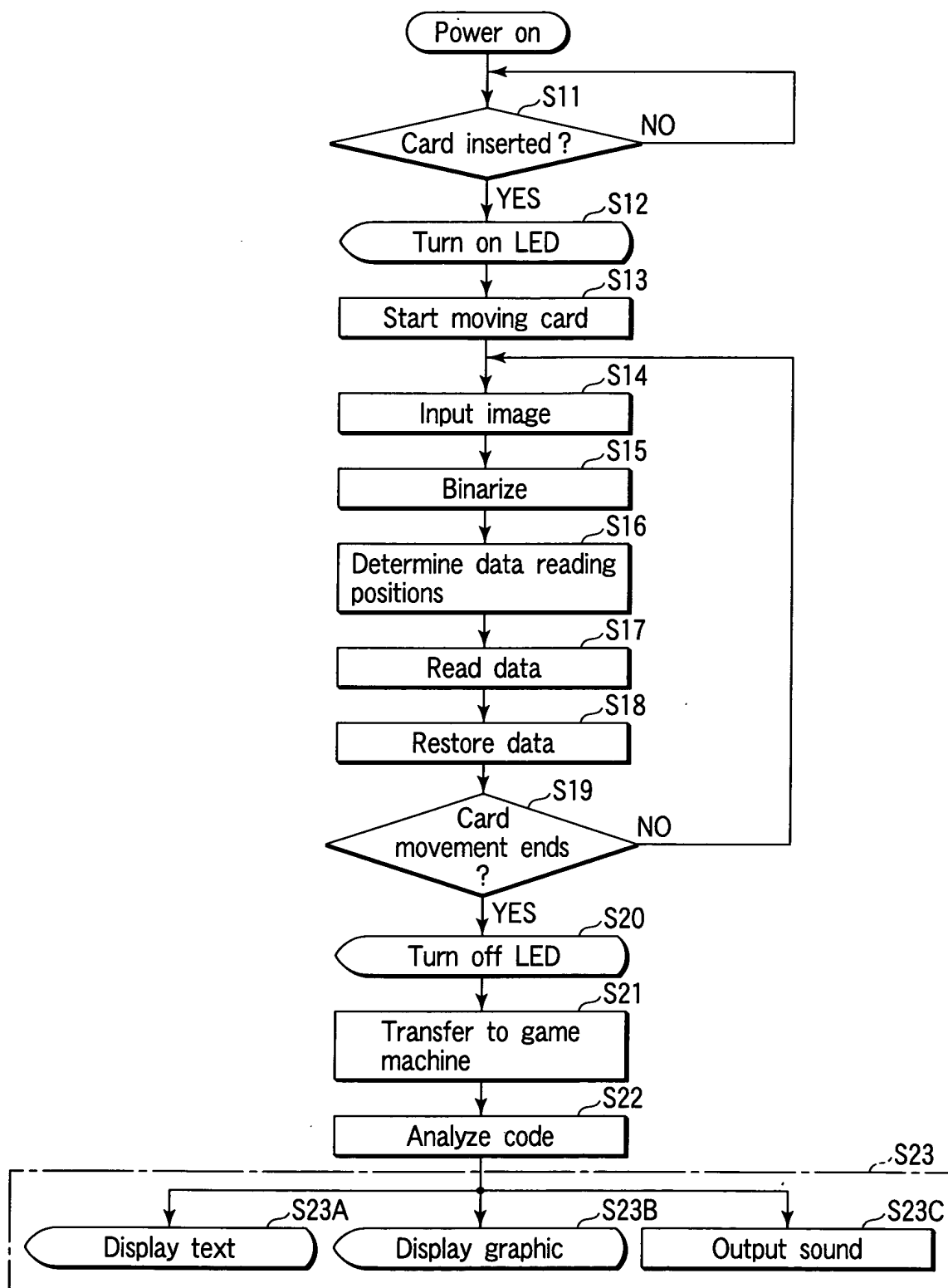


FIG. 43

Error rate [0]
Animation pattern [0]
Error rate [1]
Animation pattern [1]
⋮
Error rate [n]
Animation pattern [n]

201(202)

FIG. 44

Speed	
1~10	70
11~20	20
21~30	60
31~40	50
⋮	⋮

201

FIG. 50

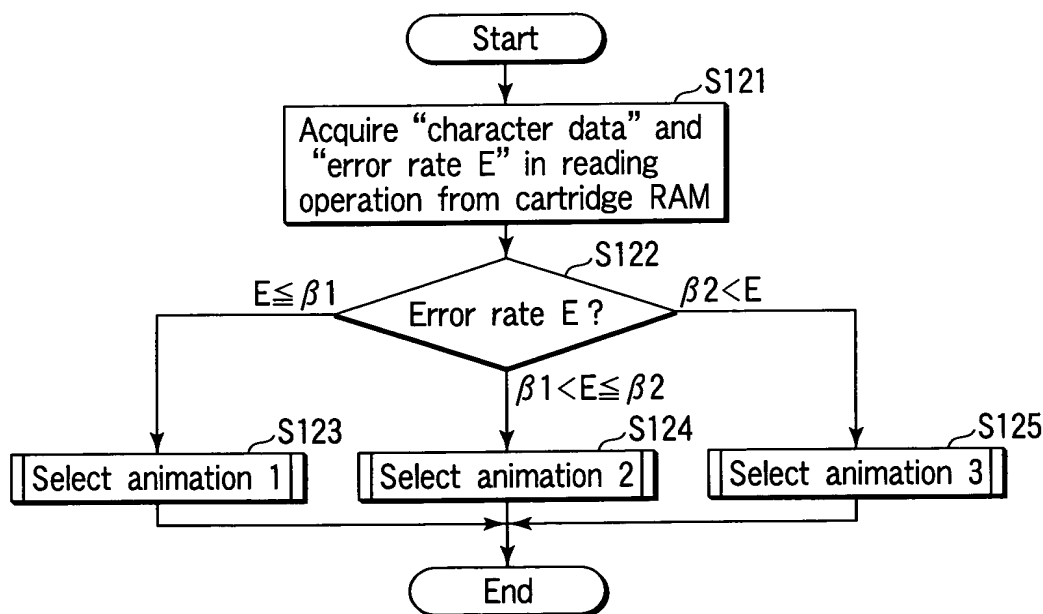


FIG. 46

```

graph TD
    Start([Start]) --> S111[Acquire "character data" and "error rate E" in reading operation from cartridge RAM]
    S111 --> S112[α ← 0]
    S112 --> S113{Error rate [α] ≤ error rate E ?}
    S113 -- YES --> S116[Acquire animation pattern [α] from cartridge ROM and display in combination with "character data"]
    S113 -- NO --> S114[α ← α + 1]
    S114 --> S115{α ≤ n ?}
    S115 -- YES --> S113
    S115 -- NO --> Error([Error])
    S116 --> End([End])
  
```

FIG. 45

1008422.030402

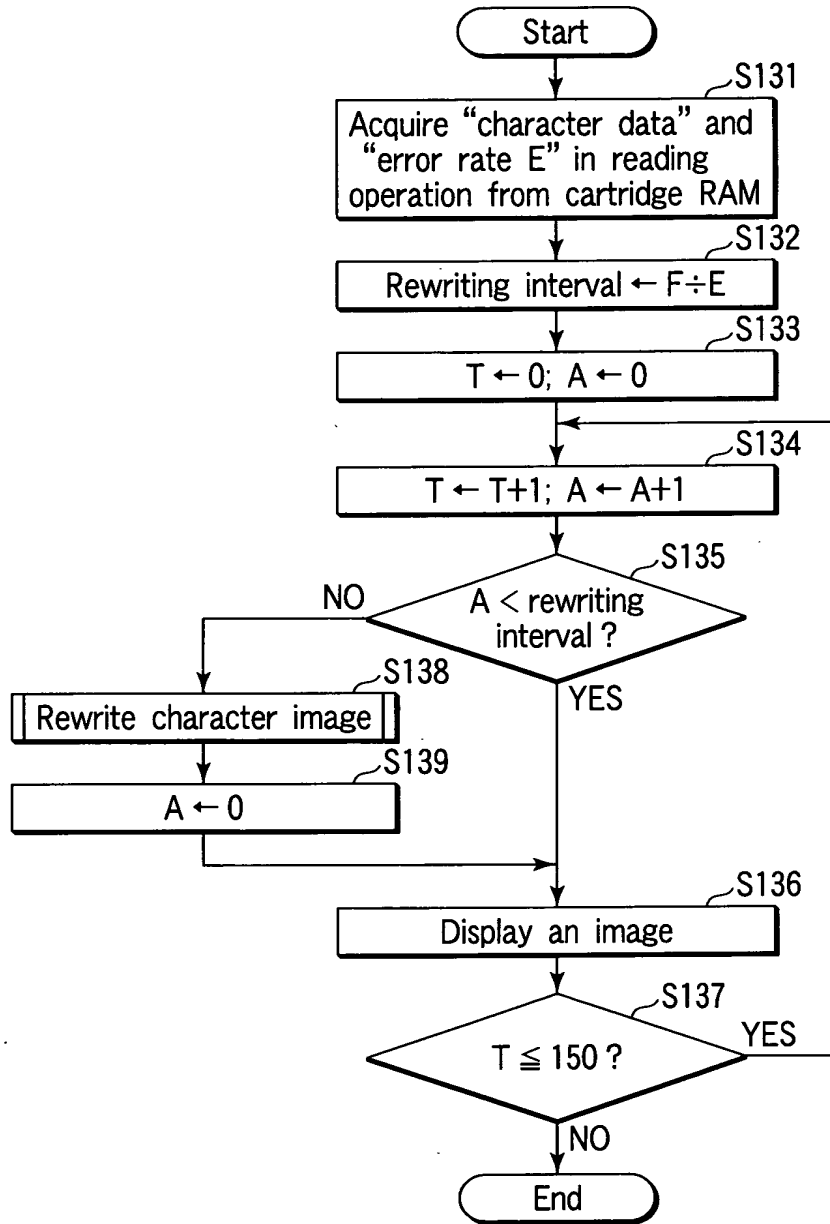


FIG. 47

10086422-030102

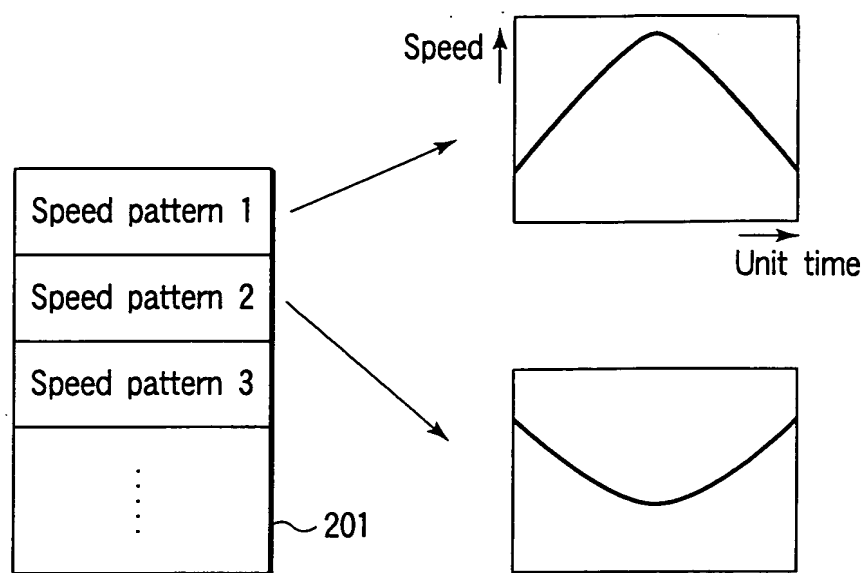


FIG. 48

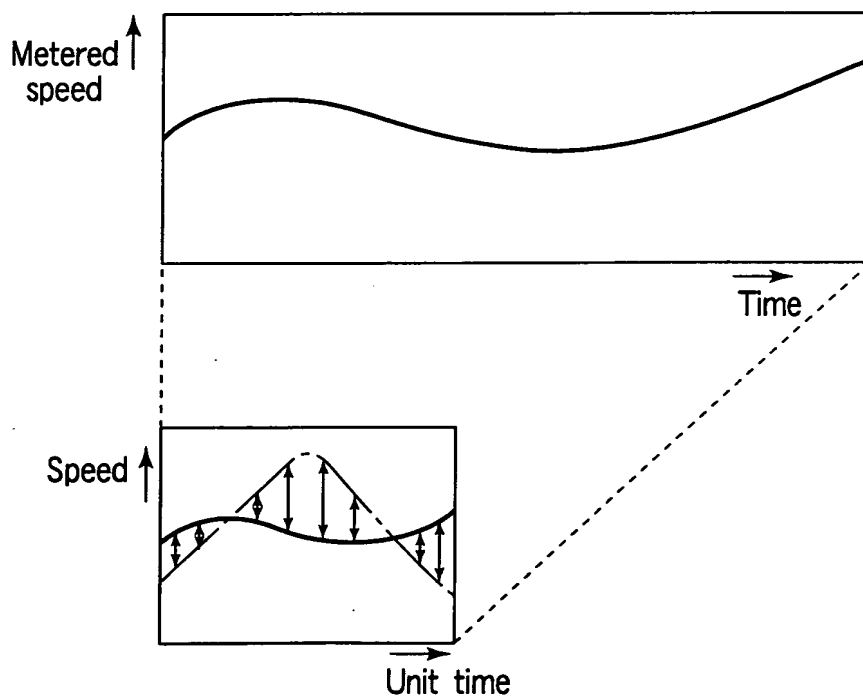


FIG. 49